

# Descriptive Complexity of Matrix and Graph-Controlled Insertion-Deletion Systems

Lakshmanan Kuppusamy  
School of Computer Science & Engineering  
VIT, Vellore - 632 014. klakshma@vit.ac.in

**Abstract:** Lila Kari introduced the *Insertion-deletion* system (abbreviated as *ins-del* system) in formal language theory. Informally, the insertion and deletion operations are defined as follows: if a string  $w$  is inserted between two parts  $u$  and  $v$  of a string  $uv$  to get  $uwv$ , then we call the operation insertion, whereas if a substring  $x$  is deleted from a string  $uxv$  to get  $uv$ , then we call the operation deletion. Suffixes of  $u$  and prefixes of  $v$  are called left and right context respectively. An ins-del system is well described by its size, denoted by  $(n, i', i''; m, j', j'')$  where the parameters from left to right denote (i) the maximal length of the insertion string (ii) the maximal length of the left context in insertion rules (iii) the maximal length of the right context used in insertion rules (iv)-(vi) denote the similar things in deletion rules.

Computational completeness for ins-del systems can even be achieved with rule size  $(1, 1, 1; 1, 1, 1)$  but with no rule size strictly smaller than this. This fact has motivated to study ins-del systems in combination with regulation mechanisms and to achieve the computational completeness with smaller/trade-off size than  $(1, 1, 1; 1, 1, 1)$ . Some of the important variants of ins-del systems are graph-controlled ins-del (GCID) systems, matrix ins-del (MID) system. In matrix ins-del system, the rules are in the form of a matrix and a matrix is a set of ins-del rules. During the derivation, if a matrix is chosen, then all the rules of the matrix are applied in sequentially and in order to the derived string. In graph-controlled ins-del system, there are several components and each component has a set of rules. A transition is performed on the string based on any applicable rule in the current component and the resultant string is moved to the target component specified in the rule itself.

In this talk, we see some computational completeness results of matrix and graph-controlled ins-del systems, reducing the ID size, say, to  $(1, 1, 0, 1, 1, 0)$  at the expense of increasing other measures of descriptive complexity. If time permits, we will also see representation of linear languages using these systems with their descriptive complexity measure sizes.