

# Undecidable Problems

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## Diagonalization

Diagonalization-based proof is schematically performed in the following way:

- (1) Assume that  $\rho L$  is decidable, and consider a Turing decider  $D$  such that  $L(D) = \rho L$ .
- (2) From  $D$ , construct another Turing decider  $O$ ; then, by using diagonalization technique, apply  $O$  on its own description  $\langle O \rangle$  so this application results into a contradiction.
- (3) The contradiction obtained in (2) implies that the assumption in (1) is incorrect, so  $\rho L$  is undecidable.



## TM-Halting

### Problem: TM-Halting

Question: Let  $M \in \mathcal{TM}\Psi$  and  $w \in \Delta^*$ . Does  $M$  halt on  $w$ ?

Language:  $\text{TM-Halting}L = \{\langle M, w \rangle \mid M \in \mathcal{TM}\Psi, w \in \Delta^*, M \text{ halts on } w\}$ .

## Theorem

$\text{TM-Halting}L \notin \text{TD}\Phi$

Proof I/II:

- Assume that  $\text{TM-Halting}L$  is decidable.
- Then, there exists a Turing decider  $D$  such that  $L(D) = \text{TM-Halting}L$ .
- From  $D$ , construct another Turing decider  $O$  that works on every input  $w$ , where  $w = \langle M \rangle$  with  $M \in \mathcal{TM}\Psi$  as follows:
  - $O$  replaces  $w$  with  $\langle M, M \rangle$ ;
  - $O$  runs  $D$  on  $\langle M, M \rangle$ ;
  - $O$  accepts iff  $D$  rejects, and  $O$  rejects iff  $D$  accepts.



*Proof II/II:*

- That is,  $O$  accepts  $\langle M \rangle$  iff  $M$  loops on  $\langle M \rangle$ .
- As  $O$  works on every input  $w$ , it also works on  $w = \langle O \rangle$ .
- Since  $O$  accepts  $\langle M \rangle$  iff  $M$  loops on  $\langle M \rangle$  for every  $w = \langle M \rangle$ .
- This equivalence holds for  $w = \langle O \rangle$  as well.
- $O$  accepts  $\langle O \rangle$  iff  $O$  loops on  $\langle O \rangle$ .
- Thus,  $\langle O \rangle \in L(O)$  iff  $\langle O \rangle \notin L(O)$ —a contradiction.
- Therefore,  $TM\text{-Halting}L$  is undecidable.

## Theorem

$$TD\Phi \subset TM\Phi$$

*Proof:*

- Clearly,  $TD\Phi \subseteq TM\Phi$ .
- We know that  $TM\text{-Halting}L \in TD\Phi - TM\Phi$ .
- Therefore,  $TD\Phi \subset TM\Phi$ .



## *TM-Looping*

### **Problem:** *TM-Looping*

*Question:* Let  $M \in {}_{TM}\Psi$  and  $w \in \Delta^*$ . Does  $M$  loop on  $w$ ?

*Language:*  ${}_{TM}\text{-Looping}L = \{\langle M, w \rangle \mid M \in {}_{TM}\Psi, w \in \Delta^*, M \text{ loops on } w\}$ .

To prove the undecidability of  ${}_{TM}\text{-Looping}L$ , we first establish the following two theorems.

## Theorem

${}_{TM}\text{-Looping}L$  is the complement of  ${}_{TM}\text{-Halting}L$ .

## Theorem

Let  $L \subseteq \Delta^*$ .  $L \in {}_{TD}\Phi$  iff both  $L$  and  $\sim L$  are in  ${}_{TD}\Phi$ .

*Proof (only if part):*

- Let  $L$  be a decidable language.
- Then, there is  $M \in {}_{TD}\Psi$  such that  $L(M) = L$ .
- Change  $M$  on Turing machine  $N \in {}_{TM}\Psi$  where  $N$  enters a non-final state in which it keeps looping exactly when  $M$  enters the final state.



*Proof (if part):*

- Let  $L, \sim L \in \mathcal{TM}\Psi$ .
- Then, there exist  $N, O \in \mathcal{TM}\Psi$  such that  $L(N) = L$  and  $L(O) = \sim L$ .
- Clearly, for every  $w \in \Delta^*$ ,  $w \in L(N)$  or  $w \in L(O)$  and  $L(N) \cap L(O) = \emptyset$ .
- Construct Turing decider  $M$  works on every  $w \in \Delta^*$  in the following way:
  - (1)  $M$  simultaneously runs  $N$  and  $O$  on  $w$  so  $M$  executes by turns one move in  $N$  and  $O$ .
  - (2)  $M$  continues the simulation described in (1) until a move that would take  $N$  or  $O$  an accepting configuration, where  $w \in L(N)$  or  $w \in L(O)$ .
  - (3)  $M$  halts and either accepts if  $w \in L(N)$  or rejects if  $w \in L(O)$ .
- Observe that  $L(M) = L$ . Furthermore,  $M$  always halts, so  $M \in \mathcal{TD}\Psi$  and  $L \in \mathcal{TD}\Phi$ .



## Theorem

$TM\text{-Looping}L \notin TM\Phi$ .

*Proof:*

- Assume,  $TM\text{-Looping}L \in TM\Phi$ .
- $TM\text{-Looping}L$  is the complement of  $TM\text{-Halting}L$ .
- $TM\text{-Halting}L \in TM\Phi$ .
- $TM\text{-Looping}L \notin TM\Phi$ , but by assumption,  $TM\text{-Looping}L \in TM\Phi$ —a contradiction.

## Corollary

$TM\text{-Looping}L \notin TD\Phi$ .



## Reduction

Reduction-based proof is schematically performed in the following way:

- (1) Assume that  $\rho L$  is decidable, and consider a Turing decider  $D$  such that  $L(D) = \rho L$ .
- (2) Modify  $D$  to another Turing decider that would decide a well-known undecidable language—a contradiction.
- (3) The contradiction obtained in (2) implies that the assumption in (1) is incorrect, so  $\rho L$  is undecidable.



## TM-Membership

**Problem:** *TM-Membership*

*Question:* Let  $M \in \mathcal{TM}\Psi$  and  $w \in \Delta^*$ . Is  $w$  a member of  $L(M)$ ?

*Language:*  $\mathcal{TM}\text{-Membership}L = \{\langle M, w \rangle \mid M \in \mathcal{TM}\Psi, w \in \Delta^*, w \in L(M)\}$ .

## Theorem

$\mathcal{TM}\text{-Membership}L \notin \mathcal{TD}\Phi$ .

*Proof:*

- Given  $\langle M, w \rangle$ .
- Construct a Turing machine  $N$  that coincides with  $M$  except that  $N$  accepts  $x$  iff  $M$  halts on  $x$ .
- If there were a Turing decider  $D$  for  $\mathcal{TM}\text{-Membership}L$ , we could use  $D$  and this equivalence to decide  $\mathcal{TM}\text{-Halting}L$ .
- Therefore,  $D$  can not exist.
- Thus, there is no Turing decider for  $\mathcal{TM}\text{-Membership}L$ .

## Non-TM-Membership

**Problem:** *Non-TM-Membership*

*Question:* Let  $M \in \mathcal{TM}\Psi$  and  $w \in \Delta^*$ . Is  $w$  out of  $L(M)$ ?

*Language:*

*Non-TM-Membership*  $L = \{ \langle M, w \rangle \mid M \in \mathcal{TM}\Psi, w \in \Delta^*, w \notin L(M) \}$ .

## Theorem

*Non-TM-Membership*  $L \notin \mathcal{TM}\Phi$ .

*Proof:*

- Suppose that *Non-TM-Membership*  $L \in \mathcal{TM}\Phi$ .
- Clearly, *TM-Membership*  $L \in \mathcal{TM}\Phi$ .
- As obvious, *Non-TM-Membership*  $L$  is complement of *TM-Membership*  $L$ .
- Thus, *TM-Membership*  $L$  would belong to  $\mathcal{TM}\Phi$ .

## Corollary

*Non-TM-Membership*  $L \notin \mathcal{TD}\Phi$ .

## TM-Regularity

**Problem:** *TM-Regularity*

*Question:* Let  $M \in \text{TM}\Psi$  and  $w \in \Delta^*$ . Is  $L(M)$  regular?

*Language:*  $\text{TM-Regularity}L = \{\langle M \rangle \mid M \in \text{TM}\Psi, L(M) \text{ is regular}\}$ .

## Theorem

$\text{Non-TM-Regularity}L \notin \text{TM}\Phi$ .

## Other Undecidable Problems I/II

**Problem:** *CF-Equivalence*

*Question:* Let  $G, H \in \text{CF}\Psi$ . Are  $G$  and  $H$  equivalent?

*Language:*  $\text{CF-Equivalence}L = \{\langle G, H \rangle \mid G, H \in \text{CF}\Psi, L(G) = L(H)\}$ .

**Problem:** *CF-Containment*

*Question:* Let  $G, H \in \text{CF}\Psi$ . Does  $L(G)$  contain  $L(H)$ ?

*Language:*  $\text{CF-Containment}L = \{\langle G, H \rangle \mid G, H \in \text{CF}\Psi, L(H) \subseteq L(G)\}$ .



## Other Undecidable Problems II/II

### **Problem:** *CF-Intersection*

*Question:* Let  $G, H \in_{CF}\Psi$ . Is the intersection of  $G$  and  $H$  empty?

*Language:*  $CF\text{-Intersection } L = \{\langle G, H \rangle \mid G, H \in_{CF}\Psi, L(G) \cap L(H) = \emptyset\}$ .

### **Problem:** *CF-Universality*

*Question:* Let  $G \in_{CF}\Psi$ . Is  $L(G)$  equal to  $G\Delta^*$ ?






*Language:*  $CF\text{-Universality } L = \{\langle G \rangle \mid G \in_{CF}\Psi, L(G) = G\Delta^*\}$ .

### **Problem:** *CF-Ambiguity*

*Question:* Let  $G \in_{CF}\Psi$ . Is  $G$  ambiguous?

*Language:*  $CF\text{-Ambiguity } L = \{\langle G \rangle \mid G \in_{CF}\Psi, G \text{ is ambiguous}\}$ .



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Thank you for your attention!

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